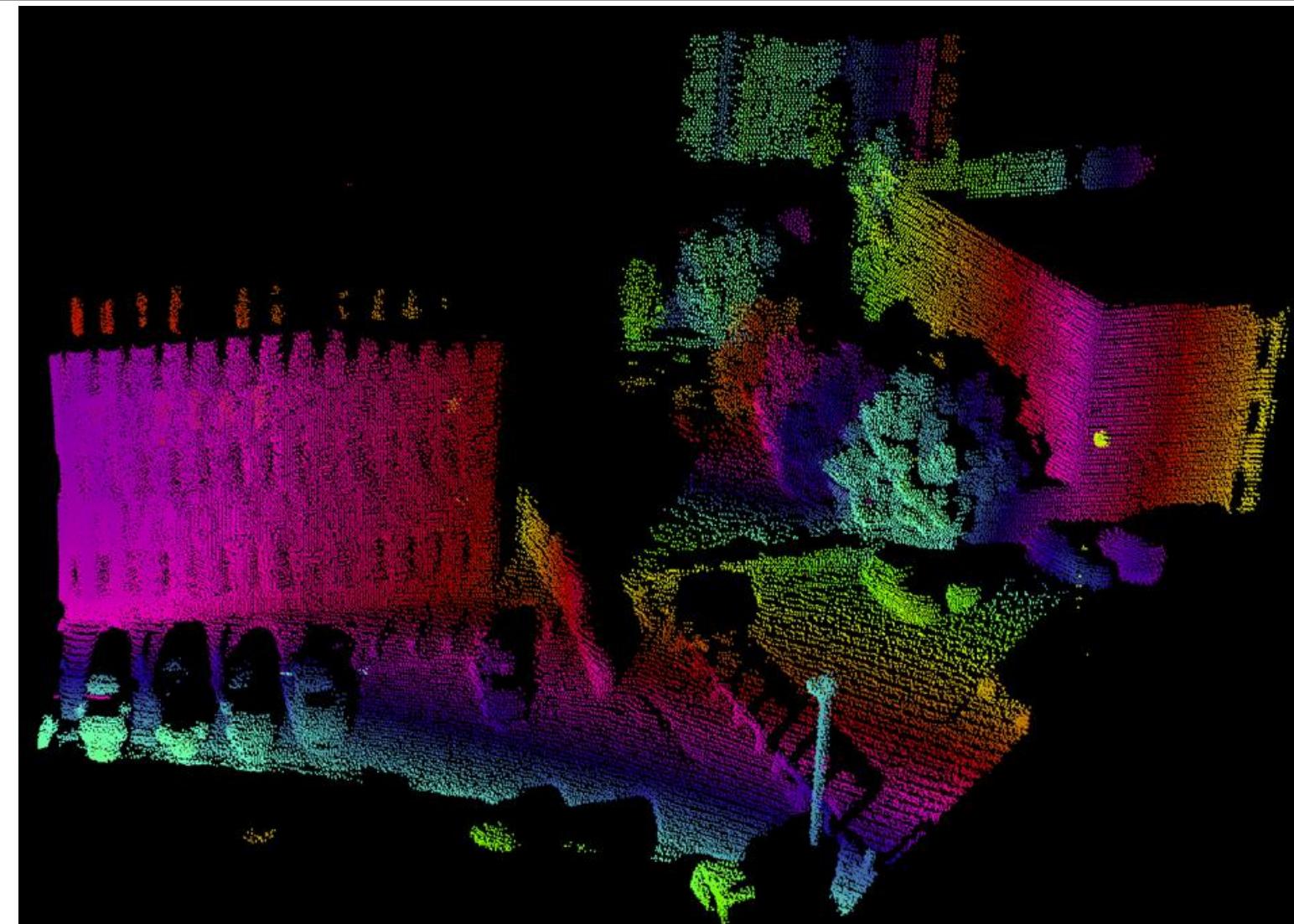


LIDAR-based sensor for detection of small cross-section targets in complex scenarios

Santiago Royo
27/10/2025

3D LIDAR imaging



PRODUCT: Multimodal perception system



AT A GLANCE:

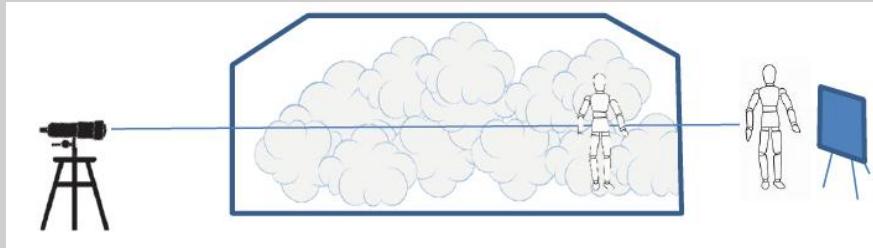
- System composed by **three imaging modes**:
 - High-res solid-state 3D LIDAR (patented)
 - RGB camera
 - Thermal camera
- Embedded **data fusion** in-house calibrated
- Embedded **AI-perception** software for automatic object detection
- Due to the triple imaging approach:
 - Minimum **false alarms**
 - Performance guaranteed in **all environmental** conditions: day/night or bad weather (rain, snow, dust and smoke)

Example use cases

DEFENSE:

Polarized LIDAR for object detection though degraded visual environments

Design of a L3CAM LIDAR combined with active polarimetric imaging for enhanced situational awareness into fog and smoke.



[dstl]

AUTOMOTIVE:

Long-range LIDAR for penetration into challenging environments

Design of a L3CAM LIDAR with controllable polarization states for penetration into fog and smoke.



Mercedes-Benz



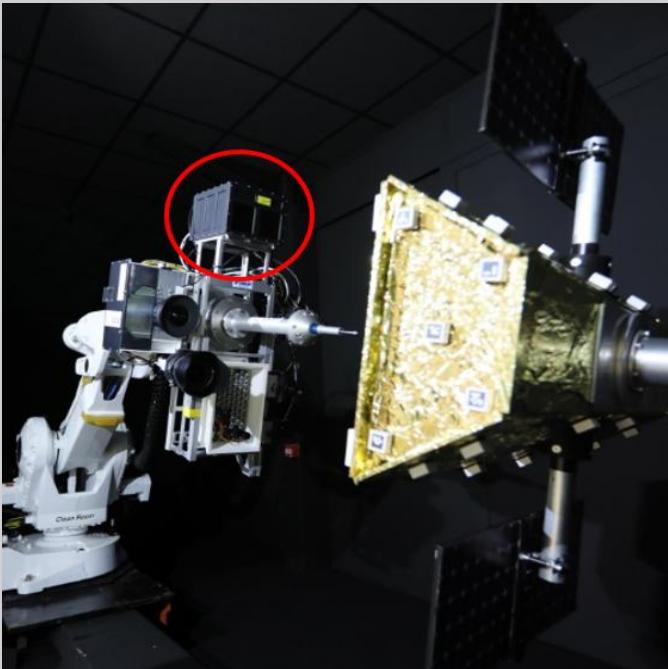
Example use cases

SPACE:



Development of a space qualified solid-state LIDAR for orbital servicing.

Design based on the L3CAM technology. Redesign for fail-safe operation and space standards.



RAILWAY:



Development of a multisensory platform for Railway Autonomous Shunting and obstacle detection applications

The project focus on the design of a custom multisensory unit that joints high-resolution LIDAR with multiple cameras (RGB and LWIR)

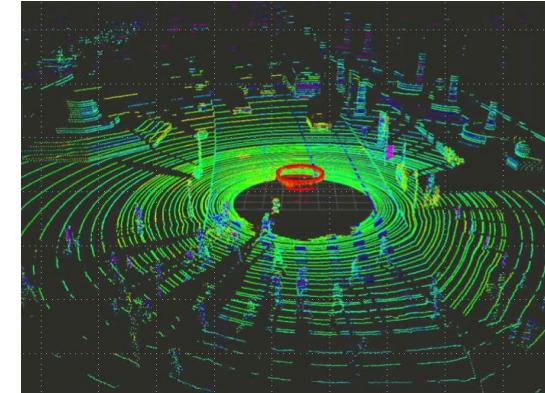


Why LIDAR for small targets?

- Reliable in complex urban scenarios



- 360° with a single unit



- Moderate LPD/ Low LPI
- Low SWaP



- Compatible with a moving platform



- Small cross-section targets
- Multi-target compatible
- Static and moving



- Wavelength agnostic
- Long ranges (km attainable)



Technology comparison

PROS

LIDAR 

- Reliable with complex scenarios
- Static and moving targets
- Low LPI, resistant to jamming
- Low SWaP and 360°

RADAR 

- 360° with a single unit
- Long range possible
- Fog penetration

EO 

- Passive solution -> good LPD/LPI
- Very high spatial resolution
- Mature technology

CONS



- Affected by fog
- Range limited to few km
- Less mature technique

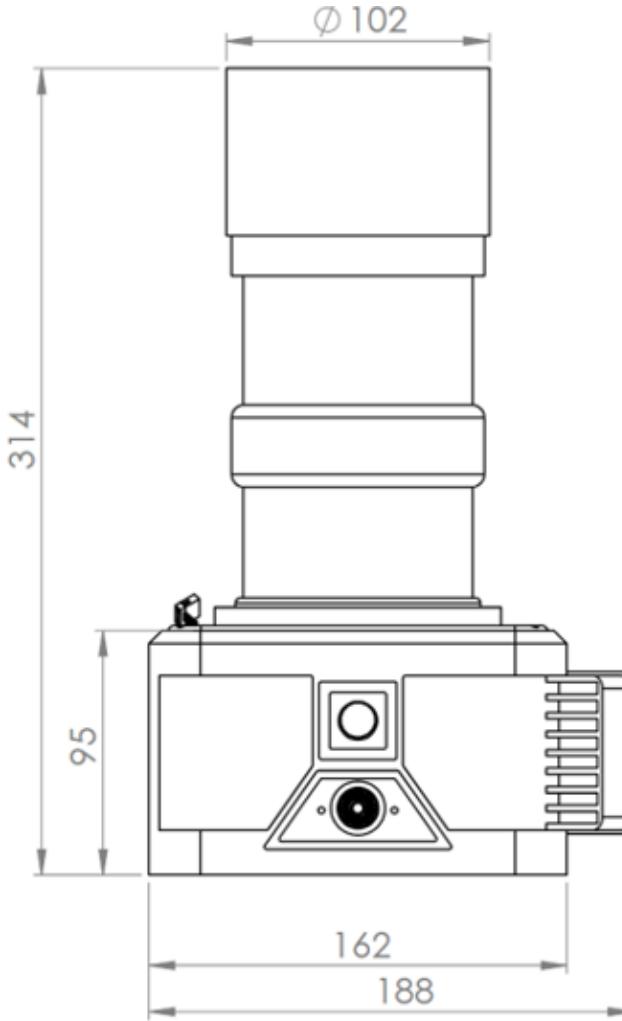


- False detections in complex scenarios
- High LPD/LPI
- Susceptible to jamming



- 360° only with multiple units
- No range information
- Sensitive to fog

AD2501 specs



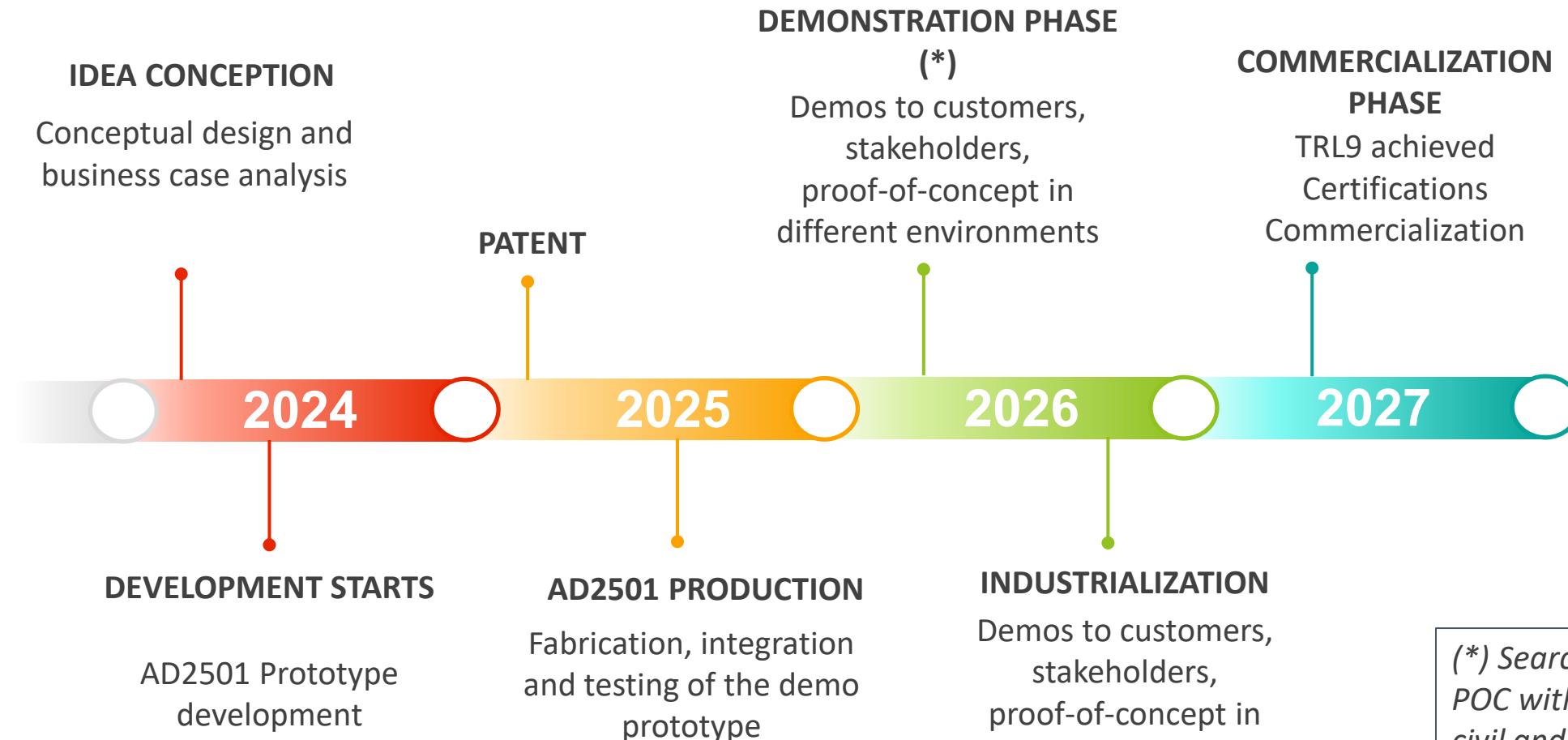
OPTICAL PERFORMANCE

LIDAR	
FOV	360 x 20 deg [HxV]
Point cloud spatial resolution	1000 x 300 px [HxV]
Angular resolution	0.36 x 0.067 deg [HxV]
Range (<i>Target diameter = 0.35m</i>)	500m @ 10% object reflectivity 1100m @ 50% object reflectivity
Angular sampling accuracy	< 0.01 deg
Point rate	600 KHz
Frame rate	2 Hz
Laser product class	Class 1 per IEC 60825-1:2007 & 2014
Range accuracy	±2 cm
Number of returns	4
Laser wavelength	1030 nm
Laser beam divergence	0.08°

MEMS-based beam steering patented concept



Development roadmap



Multimodal UAV DRI+T

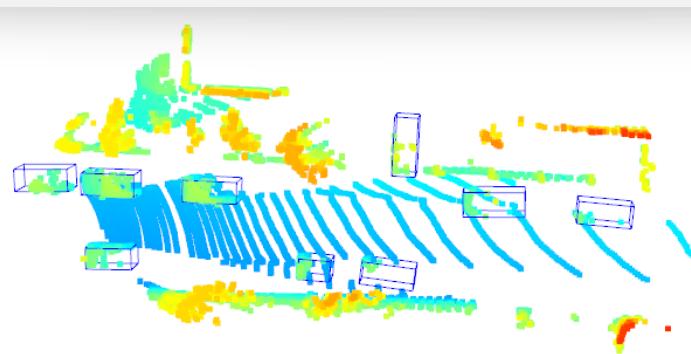
TRACKING



DETECTION



LIDAR 3D
High-density 3D data



RECOGNITION



IDENTIFICATION

**2D IMAGES**

High-resolution complementary data

Dataset	Sample 1	Sample 2	Sample 3	Sample 4
Bird				
Helicopter				
Multirotor				

Source: Samadzadegan, F., Dadras Javan, F., Ashtari Mahini, F., & Gholamshahi, M. (2022). Detection and Recognition of Drones Based on a Deep Convolutional Neural Network Using Visible Imagery. *Aerospace*, 9(1), 31. <https://doi.org/10.3390/aerospace9010031>



ROBUST AI-BASED DRI+T PERCEPTION



3D + 2D FUSION
All sensors benefits



The EPIC slide...

What can we do for you?

- Support your developments in perception systems customizing them
- Develop fail-proof systems with lidar and multimodal imaging
- Experts in MEMS mirror control for any application
- Help in your developments on vision in challenging environments, HW to SW
- Also working in free-space optics, adaptive optics,...
- Let's talk!

How can you help us?

- Searching demos and POCs in drone detection
- Looking for end users interested in advanced perception
- Working for integrators and use cases where multimodal imaging adds value
- Interest in showcasing demos for a lidar-based drone detection system

**THANKS FOR YOUR
ATTENTION!**

■ **Contact information**

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