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A member of the JENOPTIK Group



### Centration measurement and application expertise



#### **Special lenses**

- Aspheres
- Cylinders
- IR lenses

#### **Basics lens alignment**

- Manual assembly processes
- SmartAlign: alignment w/o preadjustment



#### Automated lens alignment

- Doublet alignment wrt lens barrel
- Doublet alignment wrt optical axis
- Single lens on arbor



Bonding Lens to cell in 2D and 5D



### State of the art for the measurement of aspheres

ocusing autocollimator Paraxial area only No information on the tilting of the asphere	<ul> <li>Profile recognition (tactile)</li> <li>Direct topography measurement</li> <li>Affordable</li> <li>Damage to the optical surface</li> <li>No referencing of the lower surface</li> <li>Time-consuming, complete surface scan</li> </ul>	<ul> <li>Scanning optical distance sensor</li> <li>+ Complete topography measurement (with metrology frame)</li> <li>- Reference of the lower surface requires special sample holders and additional measurements of reference (3 balls or flange and cylinder surfaces of swap holder)</li> </ul>		
nterferometer + CGH Complete topography measurement Fast Expensive CGH is required for any asphere design No referencing of the lower	<ul> <li>Stitching Interferometer</li> <li>Full topography measurement</li> <li>Flexible</li> <li>Expensive</li> <li>No referencing of the lower surface</li> </ul>	<ul> <li>Focusing autocollimator with optical distance sensor</li> <li>+ Direct measurement of the lower lens surface</li> <li>+ Fast</li> <li>- No complete topography measurement (few form errors recognizable)</li> </ul>		

surface



## Centration testing of aspheres

- 1. Measurement of paraxial centering based on the autocollimator
- 2. Alignment to the rotation axis
- 3. Measurement of asphere tilt by non-contact distance sensor
- 4. Optional: measurement of further reference surfaces

or in case of alignment turning

4. Machining of reference surfaces for further assembly





### Measurement principle AspheroCheck<sup>®</sup> UP



- Amplitude A proportional to the tilting of the aspherical surface.
- Phase Φ indicates the azimuth angle of tilting.
- Automatic compensation of the influence of the displacement due to the paraxial centering error known from the autocollimator measurement.



## Solutions

### AspheroCheck<sup>®</sup> UP



The specialist for highest precision aspheric lens measurement

#### AspheroCheck<sup>®</sup> on OptiCentric<sup>®</sup> 101



Universal and customizable usage

#### AspheroCheck<sup>®</sup> on ATS



Make perfectly aligned aspheres for assembly



# **Double-sided** aspheres

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#### Method 1

Sequential measurement of both asphere axes

- Azimuth orientation of both measurements must be known
   "flip" holder
- Combination of two datasets using the (paraxial) optical axis as reference; no external reference needed
- Cycle time < 3 min







## AspheroFlip

Special holder for double-sided aspheres:

- > AspheroFlip
- Measurement of the asphere axis is always performed from the top
- Lens is flipped
- Fitting pins ensure tight azimuth tolerance and define axis of rotation between measurements

#### Available for:

- OptiCentric<sup>®</sup> 101
- AspheroCheck<sup>®</sup> UP





## Lens flipping





#### Sample:

- Biconvex double-aspheric lens
- Diameter: 25 mm (Øe 22.5 mm)
- Aspheric parameters same on both sides

#### Measurement:

- Using AspheroCheck<sup>®</sup> UP
- Automated (paraxial) optical axis alignment
- Automated sensor measurement R = 10 mm conversion factor = 2.1 arcmin / μm
- 5 repetitions per side





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S1

۷s.

S2

#### Sample:

- Biconvex double-aspheric lens
- Diameter: 25 mm (Øe 22.5 mm)
- Aspheric parameters same on both sides

#### Measurement:

- Using AspheroCheck<sup>®</sup> UP
- Automated (paraxial) optical axis alignment
- Automated sensor measurement R = 10 mm <u>conver</u>sion factor = 2.1 arcmin / μm
- 5 full repetitions (including alignment)

			S2 asphere axis with respect to S1 asphere axis								
				Shift [µm]			Tilt [']				
		#	Z [mm]	Х	Y	Abs	Х	Υ	Abs		
		1	0.0	-4.8	65.1	65.3	1.17	-8.18	8.26		
		2	0.0	-3.4	64.8	64.9	1.26	-8.06	8.15		
		3	0.0	-3.6	65.6	65.7	1.23	-8.27	8.36		
		4	0.0	-4.8	65.3	65.5	1.23	-8.20	8.29		
		5	0.0	-3.6	65.0	65.1	1.03	-8.15	8.21		
		ave	rage	-4.0	65.2	65.3	1.18	-8.17	8.26		
		std.	dev.	0.6	0.3	0.3	0.08	0.07	0.07		
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	-100 -50	0 X Iu	50	100	-100	-50 0 V lun	50	100	-100	-50 0 X [um]	50 100



#### Method 2:

Direct measurement of top and bottom surfaces with distance sensor(s)

- Sequential measurement of surf #1 and #2 by automated sensor positioning of single sensor or
- Parallel measurement in dual sensor setup; cycle time <1min
- Needs custom lens holder design to grant physical access to bottom surface
- Limitations for some sample geometries (small lenses, biconcave lenses)





### Conclusions and summary

- Same measurement principle is established on different platforms
- We cover applications from asphere testing to apshere assembly
- All devices support
  - Prealignment (simplifies interpretation of sensor signals)
  - Sensor fusion (each sensor does what it can do best
  - What you see is what you get (you can see a simple measurement, no need to rely on point cloud analysis)
- TRIOPTICS has provided solutions for small (2mm) to large (>200 mm), single- and double-sided, plastic and glass, IR and many VIS applications
- Double-sided asphere measurement without external references using the paraxial optical axis as reference (!)







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