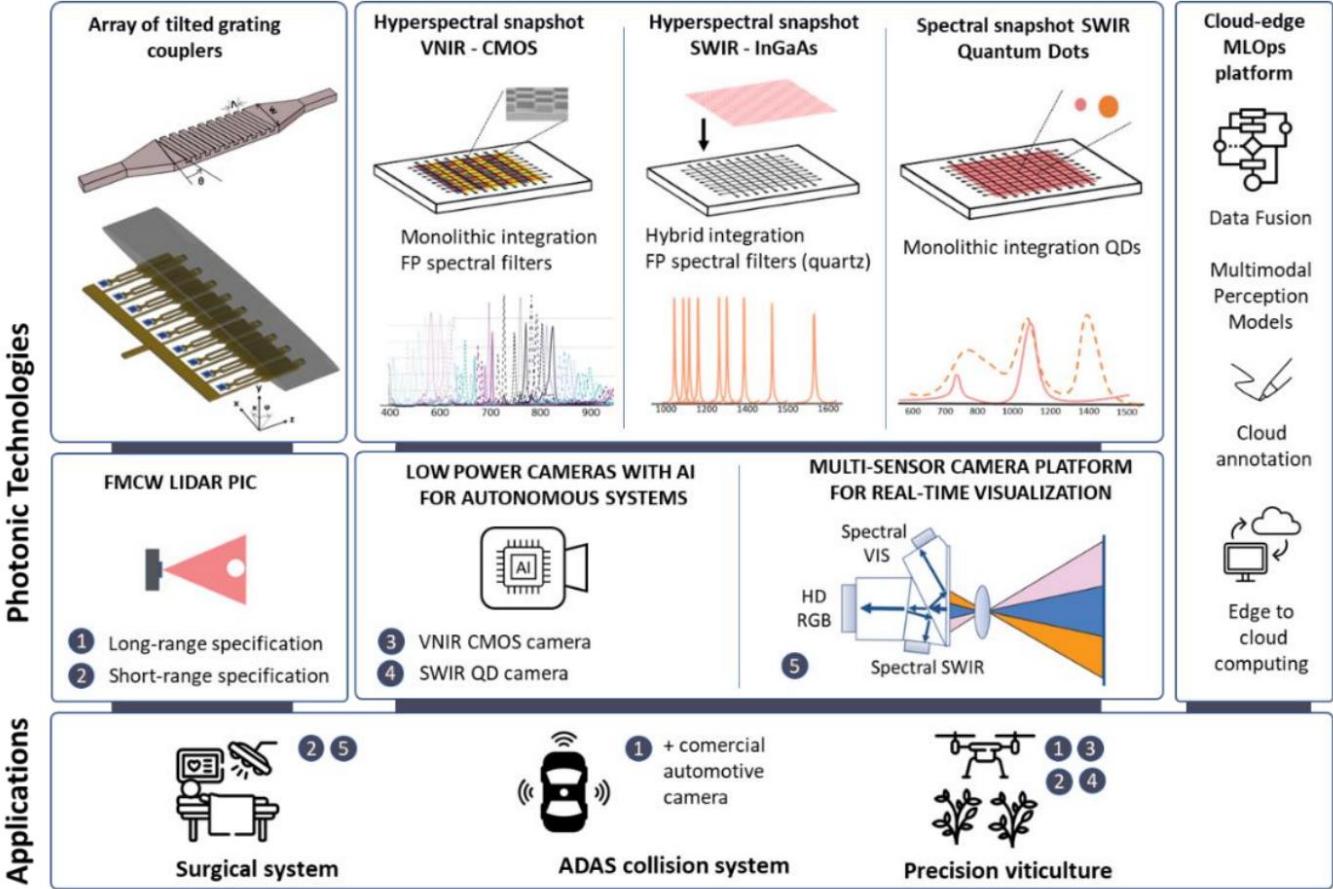




RETINA: Multimodal Photonics Sensor Systems

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RETINA: On-chip LiDAR and snapshot spectral imagers combined for smart multimodal perception in precision applications



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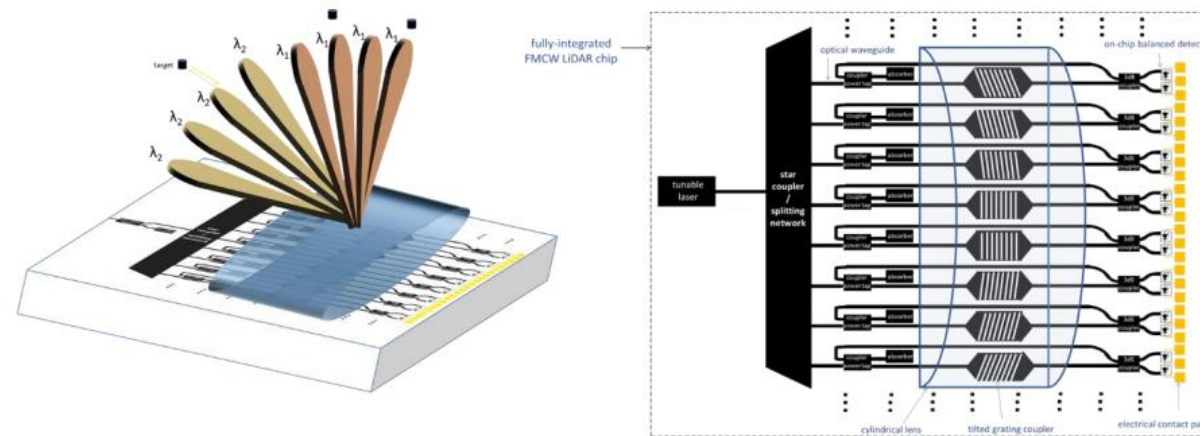
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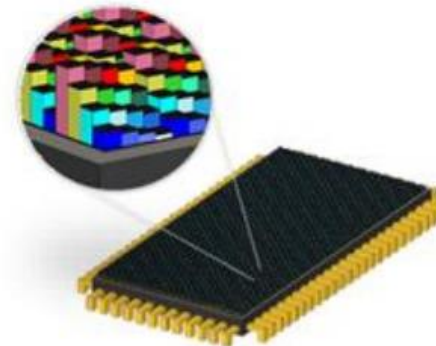
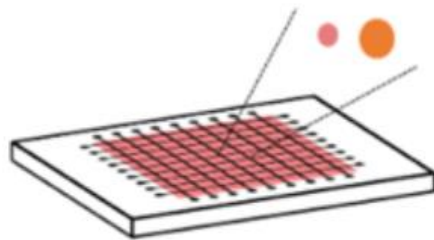
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• PIC-based LiDAR

- Tilted grating coupler array for beam steering
- Modulation: Frequency Modulated Continuous Wave (FMCW)
- Fabricated on an InP substrate
- Different packaging approaches will be studied
- Two specifications: long and short-range
- Several design-fabrication interactions

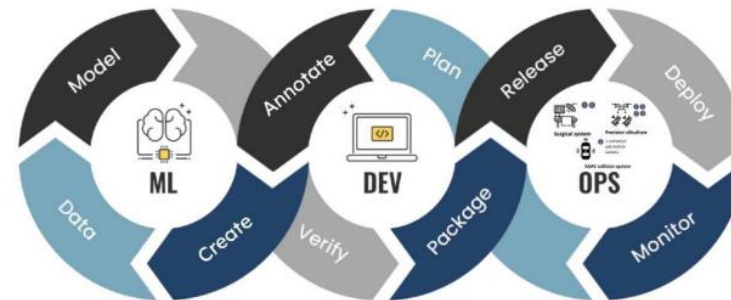
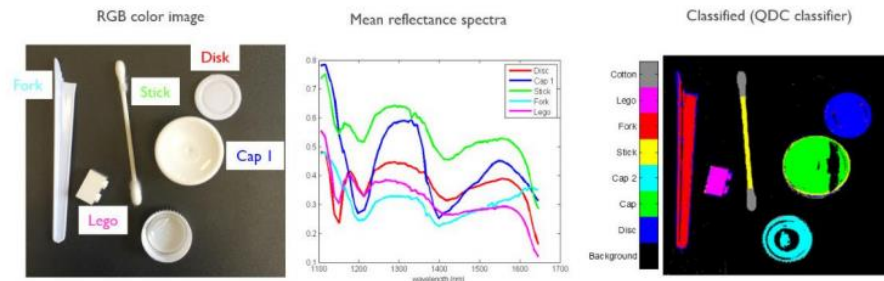


- **Snapshot spectral sensors**
 - Several approaches:
 - Q-Dot based SWIR sensor
 - Pixel level band-pass optical filters integrated in new generation imagers:
 - CMOS for VNIR
 - InGaAs for SWIR
 - These sensors will be integrated in two different modules:
 - Multi-sensor camera platform
 - Ultra low-power for spectral imaging



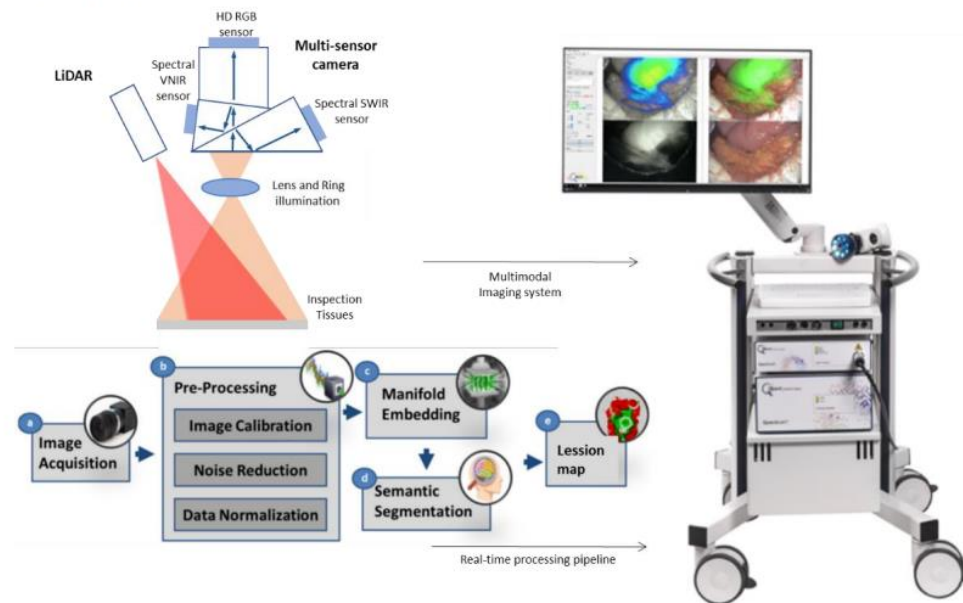
- **Machine-learning algorithms**

- Cloud-based MLOps platform for data ingestion, data annotation and model prototyping, training and validation
- Specific data elaboration techniques, data fusion and ML models
- Edge deployment of the ML models



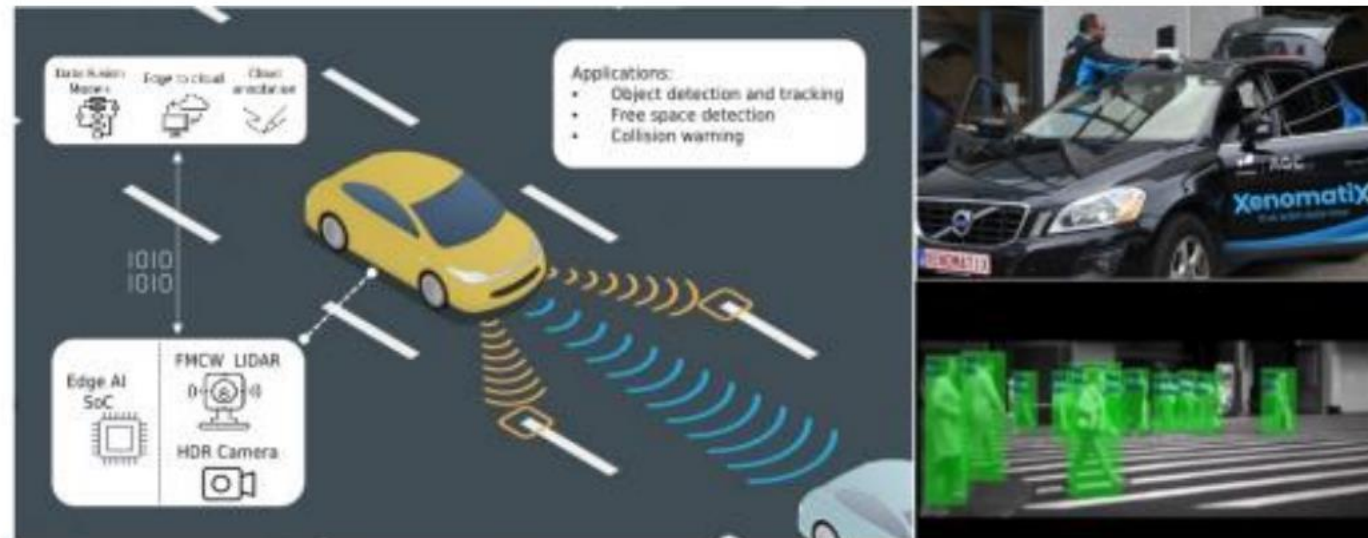
Use Case #1: Multimodal surgery support system for tissues lesions visualization

- Detect and measure tissue lesions' position, size and shape even in the presence of obscurants such as blood
- Sensors:
 - Short-range LIDAR
 - SWIR & VNIR spectral Imagers
 - Commercial RGB camera



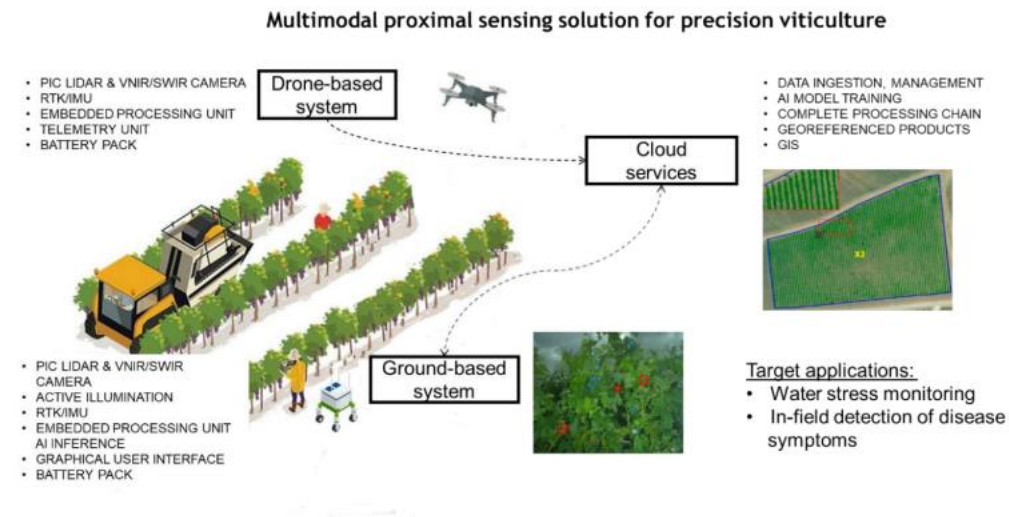
Use Case #2: Multimodal sensing for obstacles and collision detection under complex weathering conditions

- Collision avoidance will require to detect and measure people and objects' position, size and shape, as well as distance and motion ahead of and around a vehicle in any weather and light conditions.
- Sensors:
 - Long-range LIDAR
 - Commercial camera



Use Case #3: Multimodal proximal sensing solution for estimating critical parameters in viticulture

- RETINA will provide a tailored multi-modal monitoring solution to support the implementation of precision viticulture programs. The demonstration in the project will be focused on supporting the following three:
 - Water stress monitoring: a novel methodology for assessing vineyard water status;
 - Early detection of disease: in field detection grapevine trunk diseases (GTD);
 - Productivity forecast: real time estimation of harvest quantity.
- Sensors:
 - Ground-based system:
 - Short-range LIDAR
 - SWIR & VNIR spectral Imagers
 - Drone-based system:
 - Long-range LIDAR
 - SWIR & VNIR spectral Imagers



Summary

OBJ 1. To develop a novel concept of highly scalable PIC-based LIDAR

OBJ 2. To develop snapshot spectral imagers for high resolution and cost-efficient sensory systems

OBJ 3. To set up innovative software techniques and digital services for the deployment of reliable and accurate application-driven sensing platform

OBJ 4.- To support the technology leadership of EU photonic-based ecosystem by boosting growth in strategic industries



Thank you for your attention!



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OBJ 1. To develop a novel concept of highly scalable PIC-based LIDAR

- a) Solid state passive optical beamforming -based on a Tilted Grating Coupler Array approach
- b) Frequency Modulated Continuous Wave LIDAR chips
- c) Customised optics and components packaging

KPIs: PIC-based LIDAR with angle resolution (0.1°), field of view (at least $100^\circ \times 30^\circ$), rate (20Hz), range (250m for targets with 10% reflectivity), distance precision measurement (< 0.5 cm), size (300cm^3), weight (40g), power consumption ($< 10\text{W}$) and industrialised production cost ($< 150\text{€}$).



OBJ 2. To develop snapshot spectral imagers for high resolution and cost-efficient sensory systems

- a) Quantum Dot detectors (QDs)
- b) Monolithic and hybrid integrated optical microfilters
- c) Ultra low-power camera modules for spectral imaging
- d) Multi-sensor VNIR/SWIR imaging module for real time visualisation

KPIs: Snapshot VIS-NIR camera with higher spatial resolution(>5Mpx), up to factor 3 increase in the SNR, and increased wavelength range with 31 bands in 450-850 nm. Snapshot imaging medical system covering visual to infrared range (400-1700 nm) with 9 relevant bands in 1.1-1.7 μ m range for medical application. Drone and autonomous systems ready low power (<3W) with AI inference capabilities and cost-effective QD camera of at least 1.5 Mpx, maximum pixel size of 2.5 μ m and spectrum adapted for viticulture in SWIR range (1-1.7 μ m).



OBJ 3. To set up innovative software techniques and digital services for the deployment of reliable and accurate application-driven sensing platform

- a) Application-driven multimodal sensing strategies
 - a) Tissues identification for surgical applications
 - b) ADAS vehicle collision detection system
 - c) Precision viticulture solutions for hydric status management and prediction of pathogens infections
- b) Cloud-edge MLOps platform for end-to-end machine learning pipelines based on RETINA sensor systems

KPIs: Tissues lesions identification (95% of damaged tissues properly identified, <1s latency time). ADAS vehicle collision detection (<0.15 sec latency time, 200m of monitoring distance, <1000€ L3 ADAS). Precision viticulture solutions (90% of damaged vineyards properly identified, 1m accuracy for geographical localisation). Data processing cloud platform (<5s latency for near real-time ingest of multimodal image data from edge to cloud, and 1 day iteration cycles of continuous model re-training and deployment).



Photonic integrated LIDAR and snapshot spectral imagers for scaling up multimodal perception in precision applications

- Two new technologies proposed:
 - Novel LIDAR based on PICs
 - QDs and optical microfilters for spectral imagers
- Coupled with a digital infrastructure for ML algorithms development for multimodal sensing applications.
- Validation of customised sensory systems for these sectors:
 - Healthcare -> tissue lesions visualisation supporting surgery
 - Automotive -> Autonomous vehicle safety system
 - Agriculture -> precision viticulture ground and drone-mounted platforms
- TRL 3 -> 6-7

