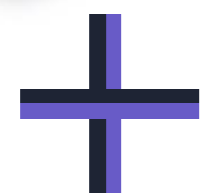
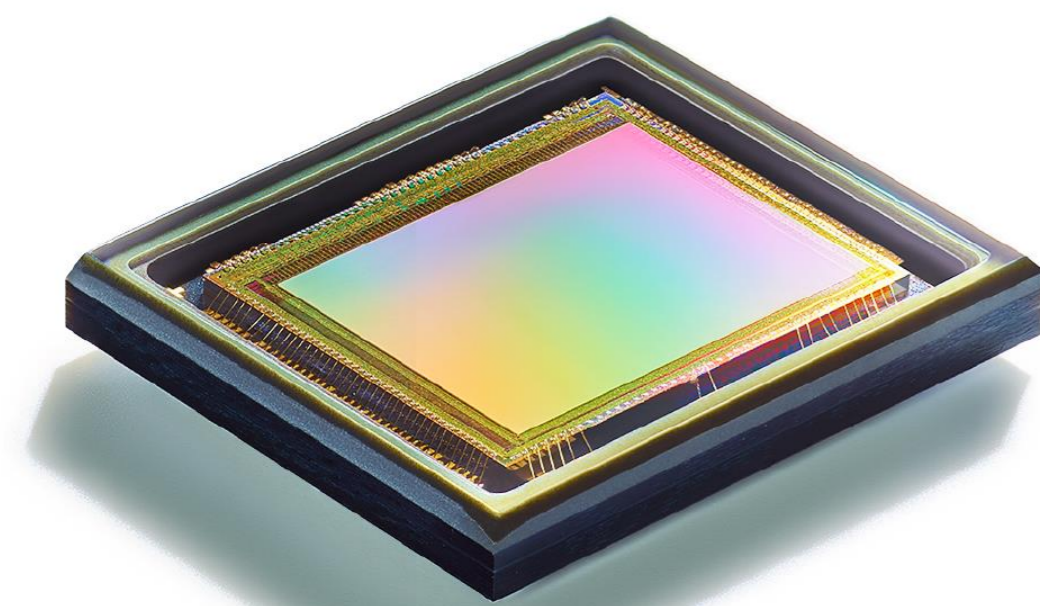




PROPHESĒE

METAVISION FOR MACHINES

NEUROMORPHIC VISION



Each pixel in Metavision® sensor embeds an intelligence logic core, enabling it to act as a neuron.

Each pixel activates itself intelligently and asynchronously depending on the amount of photons it senses.

A pixel activating itself is called an event.

Events are driven by the scene's dynamics, not an arbitrary clock. The Metavision® sensor does not have a frame rate.



This unlocks extreme time resolution of $1\mu\text{s}$

Frees from the need for exposure times

Allows for 124dB HDR and 40 millilux low-light cutoff

Generates 10 to 1000x less data

Metavision® sensor when used in combination with a VCSEL projector results in a novel Structured Light 3D sensor

Other applications are IA/robotics, mobile/wearable, automotive

EVENT-BASED STRUCTURED LIGHT



FAST, HIGH PRECISION DEPTH SENSING

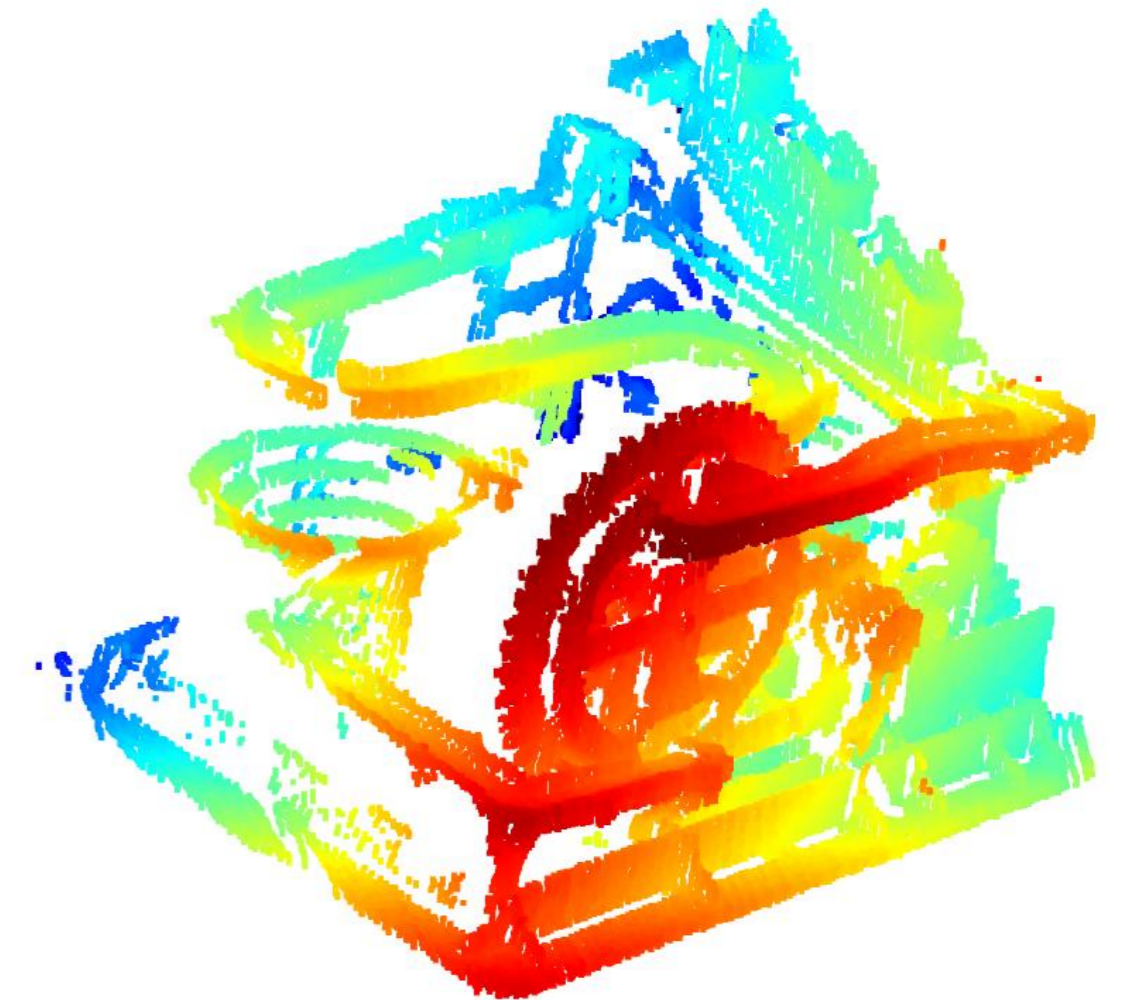
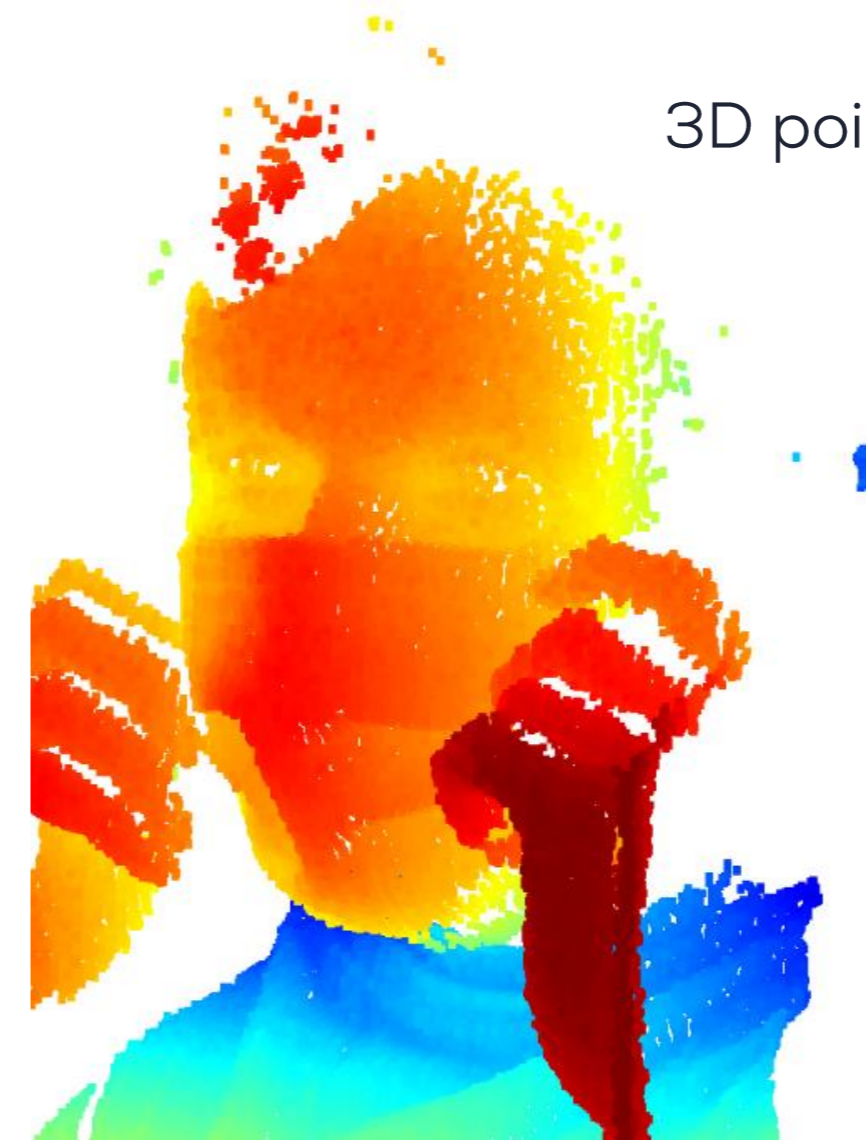
Event-based structured light

Today's state of the art depth-sensing techniques impose a trade-off between exposure time, accuracy and robustness.

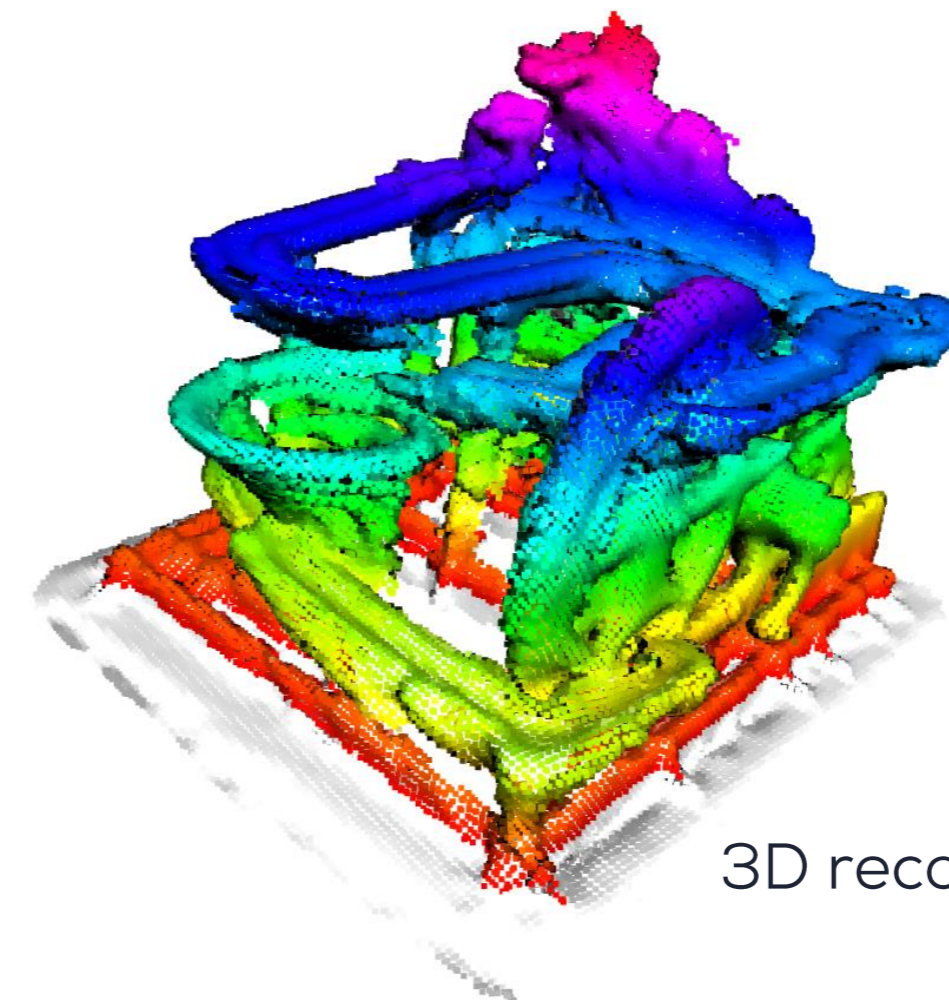
By coupling an IR projector with Metavision® sensor, the fast response time of each independent pixel allows for temporal pattern identification and extraction directly inside the sensor. This allows for:

- State of the art accuracy
- Up to 50x faster scanning times (<1ms vs. 10-33ms in average with frame-based approaches)
- Software complexity reduction (matching is not done on frames after the fact but pixel by pixel, at the sensor level)
- No motion blur (no more tradeoff between frame rate and scanning time)
- Outdoor-proof usage (ultra-fast pulse detection enables power increase while keeping eye-safe rating)

3D point cloud of a face



3D point cloud of a marble circuit



3D reconstruction using kinect fusion

ADVANTAGES

- ① WITH TEMPORAL PATTERNS, DOTS/LINES ENCODE THEIR IDS
- ① INCREASED ROBUSTNESS (ECC)
- ① MATCHING DOES NOT NEED GEOMETRY
- ① AUTO-CALIBRATION
- ① TEMPORAL PATTERN + FAST CAMERA → HIGH POINT CLOUD REFRESH RATE
- ① FAST SPARSE CAMERA → LOW POWER CONSUMPTION + LOW COMPUTATIONAL REQUIREMENTS

WE ARE LOOKING FOR

1. VCSEL projector makers partners
2. 3D point cloud users



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