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OPTICAL PHASED ARRAYS FOR AUTOMOTIVE SOLID-STATE LIDAR SYSTEMS

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EPIC Meeting on LiDAR Technologies for Automotive | Eindhoven, October 30-31, 2019

INTRODUCTION TO IMEC

35 YEARS EXPERIENCE IN TOP RESEARCH

ESTABLISHED IN 1984





IMEC (founded in 1984)

- World-leading R&D center in nanoelectronics & digital technologies
- International top talent in a unique >2B€ leading-edge fab infrastructure
- Delivering industry relevant technology solutions in ICT, Healthcare and Energy markets, serving 600+ companies
- >500 M€ R&D budget, 85% direct from industry
- >4000 people (from 90+ countries)
- **HQ** in Leuven (BE) + sites worldwide
- 24/7 operation (200 mm and 300 mm) cleanrooms (12,000 m²)

WORLD CLASS INFRASTRUCTURE



200 MM & 300 MM CLEANROOMS (24/7 OPERATION)





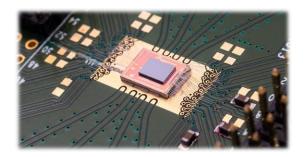








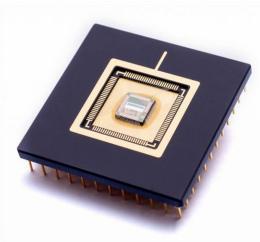
SOME AREAS OF EXPERTISE



Si and SiN Photonics



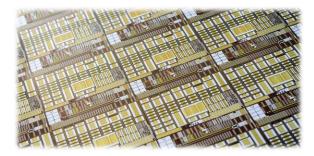
Life Sciences & Biophotonics

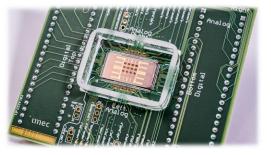


Radar Systems



CMOS and beyond CMOS





Lab-on-a-Chip

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SI PHOTONICS PLATFORM @ IMEC

State-of-the-art mature and versatile platform

56G Silicon Mach-Zehnder Modulator

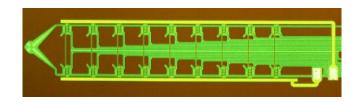




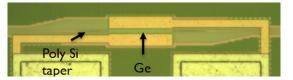
56G Silicon Ring Modulator



8+1-channel DWDM (De-)Multiplexing Filter

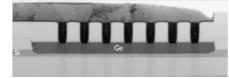


56G GeSi Electro-Absorption Modulator





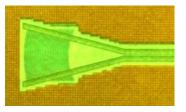
50G Ge Photodetector



50Gb/s eye diagram



Grating Coupler



Edge Coupler

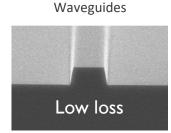


Philippe Absil et al., Optics Express 23(7), pp. 9369-78, 2015

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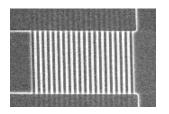
SIN PHOTONICS PLATFORM @ IMEC

A large library of experimentally verified components is available

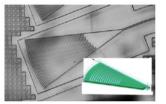




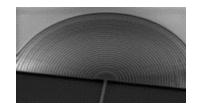
Fiber-to-WG



Low reflection

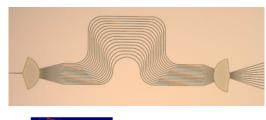


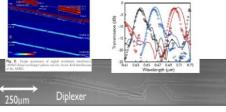
Focusing



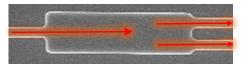
Basic spectrometers



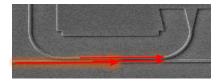




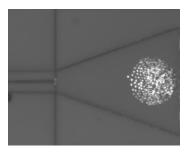
Multi-mode interferometer



Evanescent coupler



Pseudo-random



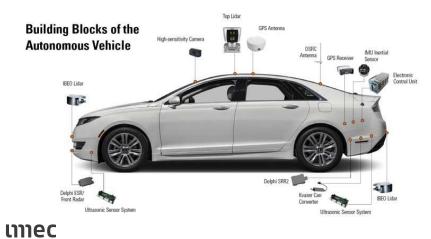
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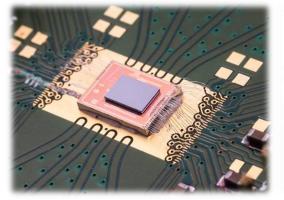
AUTOMOTIVE LIDAR

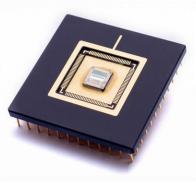
TOWARDS SOLID-STATE LIDAR SYSTEMS

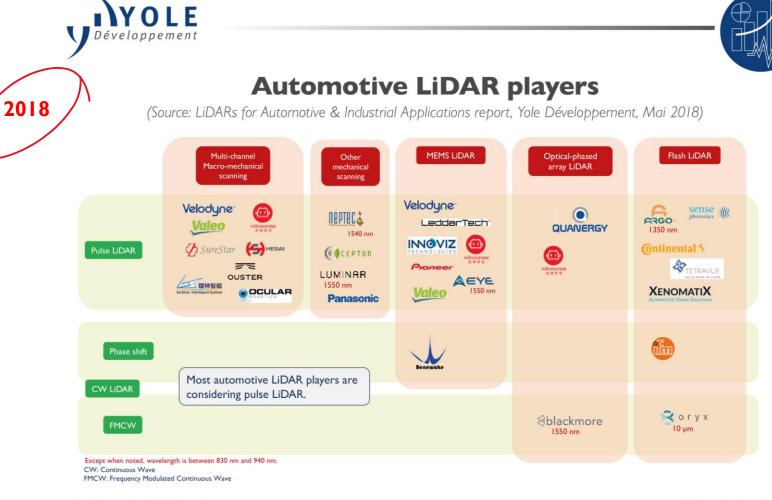


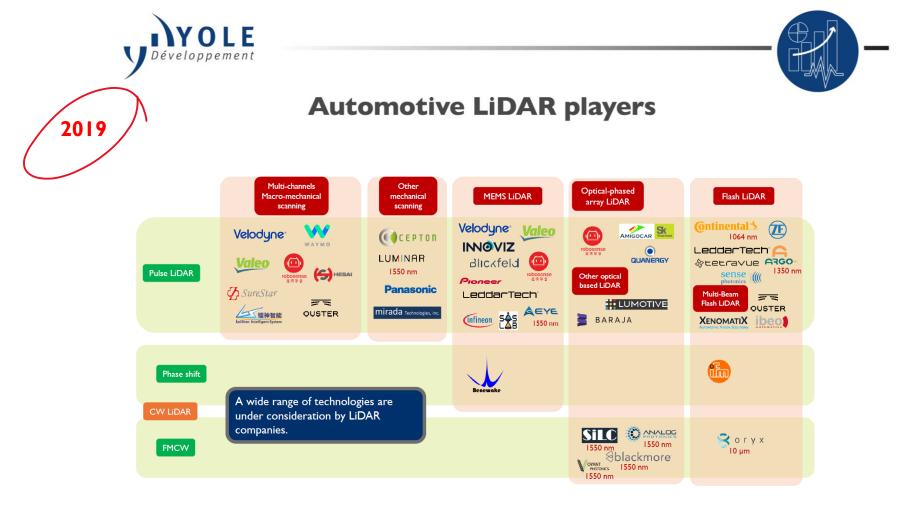












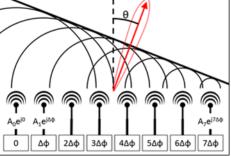
ILLUMINATION & DETECTION TECHNIQUES

Illumination techniques:

- No beam steering:
 - Flash LiDAR (uses ToF imaging arrays)
- Beam steering:
 - Bulky mechanical devices (large, heavy and costly)
 - MEMS mirrors (vibrations may be limitation)
 - Optical Phased Arrays (no-mechanical parts; can be integrated on a chip; 1D or 2D)

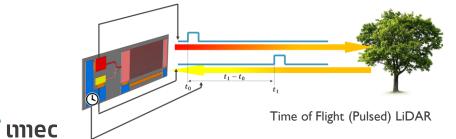
Main detection schemes:

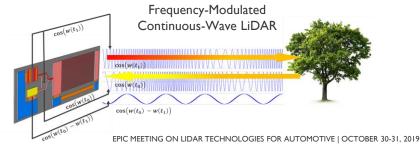




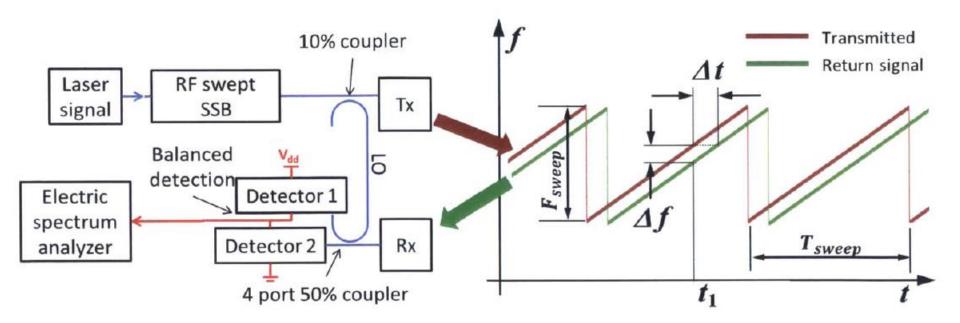
- Direct Time of Flight (ToF) High Laser power; eye safety issue (at 905nm); crosstalk/background light; noise limit
- Coherent Detection (FMCW: Frequency-Modulated CW) Shot noise limited; better dynamic range; range+velocity measurements (Doppler); complex system

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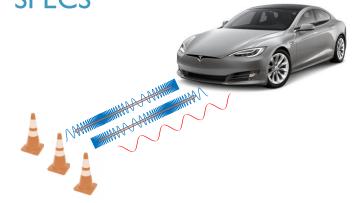
FMCW (COHERENT DETECTION)



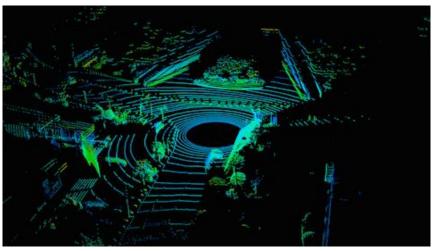
MIT (2015)

AUTOMOTIVE LIDAR GENERAL TARGET SPECS

- Sensing depth: 3D mapping
- Range: >200 m
- Cost for high volume production: <<\$1,000
- Field of view: >100° (H) × 10-30° (V)
- Angular resolution: <0.05°
- Power consumption: <50 W
- Weight: <0.5 kg
- Size: < 10 cm × 10 cm × 10 cm
- Samples per second: >>400k (frame rate: 10-30 Hz)
- Wavelength: 1550 nm (eye safe, less ambient noise)
- LiDAR engine: FMCW of TOF
- Beam delivery: Optical Phased Array (OPA)



Source: Hesai

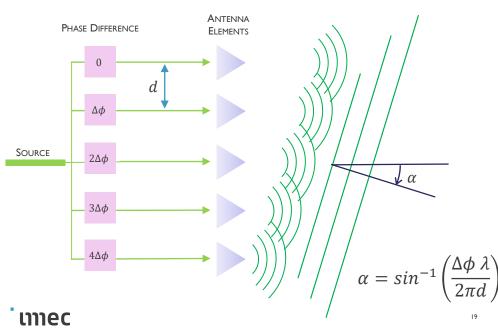


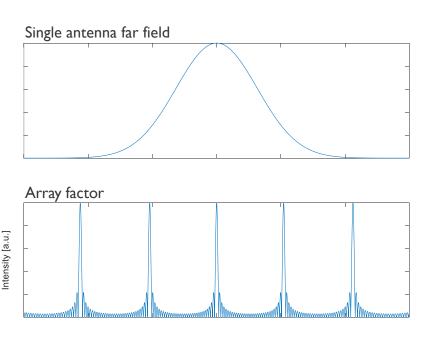
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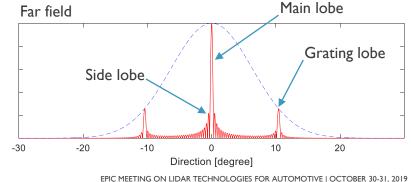
OPTICAL PHASED ARRAYS

PHASED ARRAY

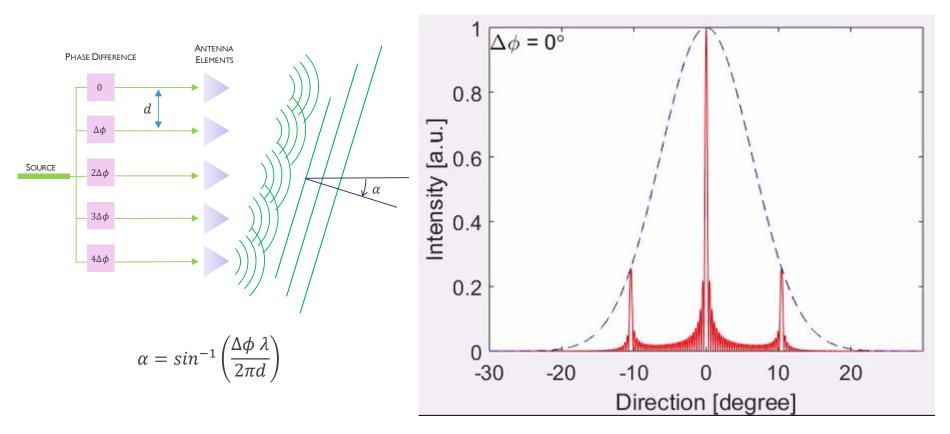
- A uniform phase difference $\Delta \phi$ between neighboring antennas results in beam steering
- Far-field radiation pattern is the product of the antenna radiation pattern and the array factor, assuming identical antennas





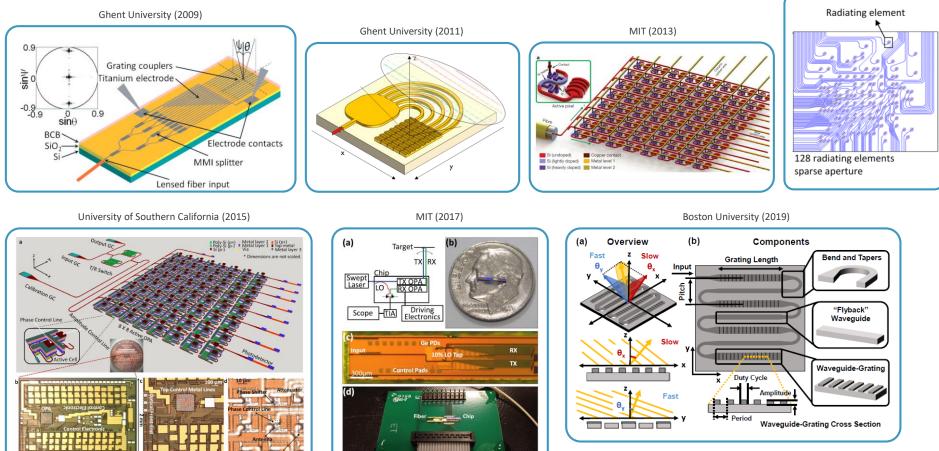


BEAM STEERING ANIMATION



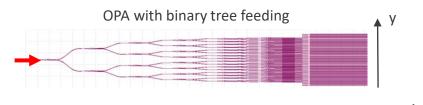
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STATE-OF-THE-ART



Caltech (2018)

ID & 2D STEERING DEMONSTRATION



OPA with binary tree architecture:

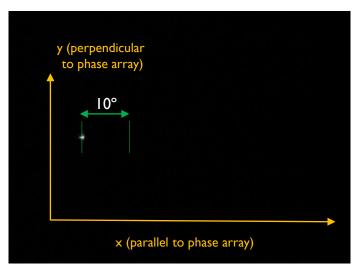
- SiN with low phase error for power routing
- Si antennas with high confinement for tight pitch
- 64 antennas at 3 μm pitch, at 1550 nm
- Wavelength tuning in the x direction
- Beam divergence: $0.47^{\circ} \times 0.4^{\circ}$

(S. Dwivedi et al., IPR 2019, IM4A.3)

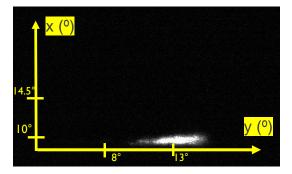
OPA with binary tree architecture:

- Si for power routing and antennas
- 8 antennas
- Thermo-optic phase shifters for tuning in the y direction
- Tuning in the x direction with source wavelength

1D λ -based steering demonstration



2D steering demonstration



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R&D OPPORTUNITIES

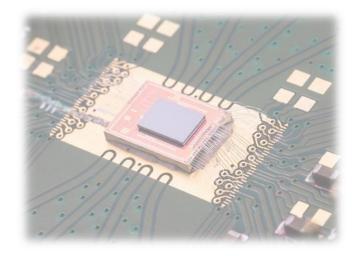
- Main challenges:
 - Insertion loss
 - Power consumption (for phase shifting)
 - Number of antennas (for large aperture size)
 - Electronics control for phase shifters (phase interrogators, ASIC)
 - Tight specs on tunable laser (linewidth, power, wavelength precision)
 - CMOS integration desired for complex electronics
- Main research activities @ imec:
 - Si and SiN hybrid platforms
 - Laser development and integration on Si/SiN
 - Chip packaging solutions
 - New materials for low-power phase shifters

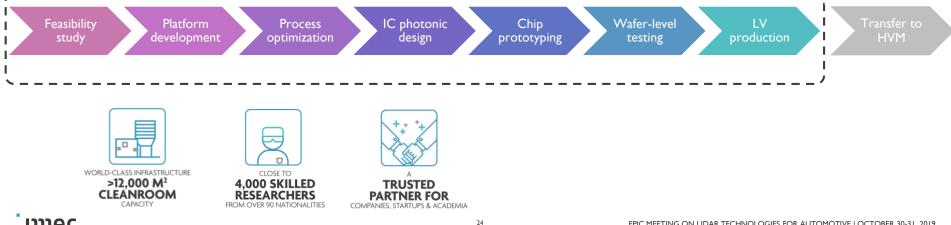


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IMEC R&D ECOSYSTEM

- What you can do for us:
 - Help us to better understand the LiDAR market dynamics
 - Expose us to your key technology needs, problems and challenges
 - Partner for system-level OPA LiDAR demonstrators
 - Collaboration in R&D projects
- What we can do for you:





embracing a better life

This presentation was presented at EPIC Meeting on LIDAR Technologies for Automotive 2019

